## Chapter 2

- 2.1 a. Spring constant, k: The change in the force per unit length change of the spring.
  - **b.** Coefficient of subgrade reaction, k':

Spring constant divided by the foundation contact area,  $k' = \frac{k}{A}$ 

c. Undamped natural circular frequency:  $\omega_n = \sqrt{\frac{k}{m}}$  rad/s

where 
$$m = \text{mass} = \frac{W}{g}$$

**d.** Undamped natural frequency:  $f_n = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$  (in Hz)

Note: Circular frequency defines the rate of oscillation in term of radians per unit time;  $2\pi$  radians being equal to one complete cycle of rotation.

- **e.** Period, *T*: The time required for the motion to begin repeating itself.
- **f.** Resonance: Resonance occurs when  $\frac{\omega_n}{\omega} = 1$
- g. Critical damping coefficient:  $c_c = 2\sqrt{km}$ where k = spring constant;  $m = \text{mass} = \frac{W}{g}$
- **h.** Damping ratio:  $D = \frac{c}{c_c} = \frac{c}{2\sqrt{km}}$

where c = viscous damping coefficient;  $c_c = \text{critical damping coefficient}$ 

i. Damped natural frequency:

$$\omega_d = \omega_n \sqrt{1 - D^2}$$

$$f_d = \sqrt{1 - D^2} f_n$$

2.2 Weight of machine + foundation, W = 400 kNSpring constant, k = 100,000 kN/m

Mass of the machine + foundation, 
$$m = \frac{W}{g} = \frac{400}{9.81} = 40.77 \frac{\text{kN}}{\text{m/s}^2}$$

Natural frequency of undamped free vibration is [Eq. (2.19)]

$$f_n = \frac{1}{2\pi} \sqrt{\frac{k}{m}} = \frac{1}{2\pi} \sqrt{\frac{100,000}{40.77}} =$$
**7.88 Hz**

From Eq. (2.18), 
$$T = \frac{1}{f_n} = \frac{1}{7.88} =$$
**0.127 s**

2.3 Weight of machine + foundation, W = 400 kNSpring constant, k = 100,000 kN/m

Static deflection of foundation is [Eq. (2.2)]

$$z_s = \frac{W}{k} = \frac{400}{100,000} = 4 \times 10^{-3} \,\mathrm{m} = 4 \,\mathrm{mm}$$

2.4 External force to which the foundation is subjected,  $Q = 35.6 \sin \omega t$  kN f = 13.33 Hz

Weight of the machine + foundation, W = 178 kNSpring constant, k = 70,000 kN/m

For this foundation, let time t = 0,  $z = z_0 = 0$ ,  $\dot{z} = v_0 = 0$ 

a. Mass of the machine + foundation,  $m = \frac{W}{g} = \frac{178}{9.81} = 18.145 \frac{\text{kN}}{\text{m/s}^2}$ 

$$\omega_n = \sqrt{\frac{k}{m}} = \sqrt{\frac{70,000}{18,145}} = 62.11 \text{ rad/s}$$

$$T = \frac{2\pi}{\omega_n} = \frac{2\pi}{62.11} = 0.101 \text{ s}$$

**b.** The frequency of loading, f = 13.33 Hz

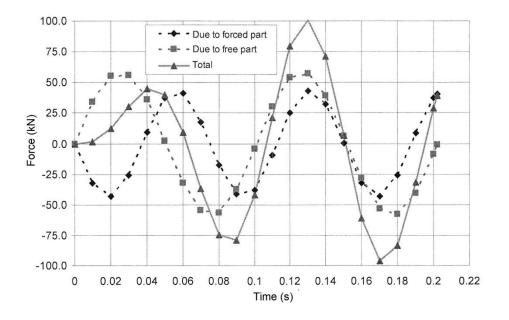
$$\omega = 2\pi f = 2\pi (13.33) = 83.75 \text{ rad/s}$$

Force due to forced part, 
$$F_1 = k \left( \frac{Q_0/k}{1 - \omega^2/\omega_n^2} \right) \sin \omega t$$
  

$$= (70,000) \left( \frac{35.6/70,000}{1 - 83.75^2/62.11^2} \right) \sin(83.75t)$$

$$= 43.51 \sin(83.75t) \text{ kN}$$

See the plot below for  $F_1$  vs. t



c. Force due to free part, 
$$F_2 = k \left( \frac{Q_0/k}{1 - \omega^2/\omega_n^2} \right) \left( -\frac{\omega}{\omega_n} \sin \omega_n t \right)$$
  

$$= 70,000 \left( \frac{35.6/70,000}{1 - 83.75^2/62.11^2} \right) \left( -\frac{83.75}{62.11} \sin(62.11t) \right)$$

$$= 58.67 \sin(62.11t) \text{ kN}$$

See the plot above in Part **b** for  $F_2$  vs. t.

**d.** Total dynamic force on the subgrade:

$$F = F_1 + F_2 = -43.51\sin(83.75t) + 58.67(62.11t) \text{ kN}$$

The plot of variation of the dynamic force on the subgrade of the foundation due to (a) forced part, (b) free part, and (c) total of the response for time t = 0 to t = 2T is shown in the figure above (Part **b**).

2.5 The natural frequency of the undamped free vibration of the spring mass system is given by  $f_n = \frac{1}{2\pi} \sqrt{\frac{k_{eq}}{m}} \quad \text{where } k_{eq} = \text{equivalent stiffness of the spring system}$ 

For springs attached in series, the equivalent stiffness is given by

$$\frac{1}{k_{eq}} = \frac{1}{k_1} + \frac{1}{k_2}$$
, or  $\frac{1}{k_{eq}} = \frac{k_1 k_2}{k_1 + k_2}$ 

The natural frequency of the given undamped free vibration spring mass system is

$$f_n = \frac{1}{2\pi} \sqrt{\frac{k_1 k_2}{k_1 + k_2} \times \frac{1}{m}}$$

2.6 The natural frequency of the undamped free vibration of the spring mass system is given by

$$f_n = \frac{1}{2\pi} \sqrt{\frac{k_{eq}}{m}}$$
 where  $k_{eq}$  = equivalent stiffness of the spring system

For springs attached in parallel, the equivalent stiffness is given by

$$k_{eq} = k_1 + k_2$$

The natural frequency of the given undamped free vibration spring mass system is

$$f_n = \frac{1}{2\pi} \sqrt{\frac{(k_1 + k_2)}{m}}$$

2.7 The natural frequency of the undamped free vibration of the spring mass system is given by

$$f_n = \frac{1}{2\pi} \sqrt{\frac{k_{eq}}{m}}$$
 where  $k_{eq}$  = equivalent stiffness of the spring system

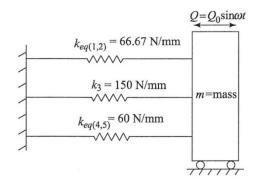
In the given spring-mass system, springs with stiffness  $k_1$  and  $k_2$  are in series. Hence, their equivalent stiffness is

$$k_{eq(1,2)} = \frac{k_1 k_2}{k_1 + k_2} = \frac{100 \times 200}{100 + 200} = \frac{20,000}{300} = 66.67 \text{ N/mm}$$

Similarly, springs with stiffness  $k_4$  and  $k_5$  are in series. Hence, their equivalent stiffness is

$$k_{eq(4,5)} = \frac{k_4 k_5}{k_4 + k_5} = \frac{100 \times 150}{100 + 150} = 60 \text{ N/mm}$$

Now, the given spring system can be reduced to three springs in series.



The resulting system will be three springs in parallel. Their equivalent stiffness is given by

$$k_{eq} = k_{eq(1,2)} + k_3 + k_{eq(4,5)} = 66.67 + 150 + 60 = 276.67 \text{ N/mm} = 276.67 \text{ kN/m}$$

The natural frequency of the undamped free vibration of the spring mass system is given by

$$f_n = \frac{1}{2\pi} \sqrt{\frac{k_{eq}}{m}} = \frac{1}{2\pi} \sqrt{\frac{267.67 \times 1000}{100}} = 8.37 \text{ Hz}$$

Time period  $T = (1/f_n) = (1/8.37) = 0.119 s$ 

2.8 Sinusoidal-varying force,  $Q = 50 \sin \omega t$  N;  $Q_0 = 50$  N;  $\omega = 47$  rad/s

$$\omega_n = \sqrt{\frac{k_{eq}}{m}} = \sqrt{\frac{276.67 \times 1000}{100}} = 52.6 \text{ rad/s}$$

Amplitude of vibration = static deflection  $z_s \times$  magnification M

$$z_s = \frac{Q_0}{k_{eq}} = \frac{50}{276.67} = 0.1807 \text{ mm}$$

From Eq. (2.34),

$$M = \frac{1}{1 - (\omega/\omega_n)^2} = \frac{1}{1 - (47/52.6)^2} = 4.96$$

Amplitude of vibration =  $0.1807 \times 4.96 = 0.896$  mm

2.9 Weight of the body, W = 135 NMass of the body, m = W/g = 135/9.81 = 13.76 kgSpring constant, k = 2600 N/mDashpot resistance, c = 0.7/(60/1000) = 11.67 N-s/m **a.** Damped natural frequency [Eq. (2.67)]

$$f_d = \sqrt{1 - D^2} f_n$$

$$D = \frac{c}{c_c} = \frac{c}{2\sqrt{km}} = \frac{11.67}{2\sqrt{2600 \times 13.76}} = 0.031$$

$$f_n = \frac{1}{2\pi} \sqrt{\frac{k}{m}} = \frac{1}{2\pi} \sqrt{\frac{2600}{13.76}} = 2.19 \text{ Hz}$$

$$f_d = \sqrt{1 - 0.031^2} \times (2.19) =$$
**2.18 Hz**

**b.** Damping ratio [Eq. (2.47b)],

$$D = \frac{c}{c_c} = \frac{c}{2\sqrt{km}} = \frac{11.67}{2\sqrt{2600 \times 13.76}} = 0.031$$

**c.** Ratio of successive amplitudes of the body is given by [Eq. (2.70)],

$$\frac{Z_n}{Z_{n+1}} = e^{\delta}$$

where 
$$\delta = \ln \left( \frac{Z_n}{Z_{n+1}} \right) = \frac{2\pi D}{\sqrt{1 - D^2}} = \frac{2\pi \times 0.031}{\sqrt{1 - 0.031^2}} = 0.195$$

$$\frac{Z_n}{Z_{n+1}} = e^{\delta} = e^{0.195} = 1.215$$

**d.** At time t = 0 s, amplitude  $Z_0 = 25$  mm.

After *n* cycles of disturbance

$$\frac{1}{n} \ln \frac{Z_0}{Z_n} = \frac{2\pi D}{\sqrt{1 - D^2}}; \quad \ln \frac{Z_0}{Z_n} = \frac{2\pi n D}{\sqrt{1 - D^2}}$$

With n = 5,

$$\ln \frac{Z_0}{Z_5} = \frac{2\pi \times 5 \times D}{\sqrt{1 - D^2}} = \frac{2\pi \times 5 \times 0.031}{\sqrt{1 - 0.031^2}} = 0.974$$

$$\frac{Z_0}{Z_5} = e^{0.974} = 2.649$$
;  $Z_5 = \frac{25}{2.649} = 9.44$  mm

After 5 cycles of disturbance, the amplitude of vibration = 9.44 mm

## **2.10** $Q_0 = 6.7 \text{ kN}$

 $\omega$  = 3100 rad/min = 51.67 rad/s Weight of machine + foundation, W = 290 kN Spring constant, k = 875 MN/m = 875,000 kN/m

Natural angular frequency, 
$$\omega_n = \sqrt{\frac{k}{m}} = \sqrt{\frac{875,000 \times 10^3}{290 \times 10^3 / 9.81}} = 172.04 \text{ rad/s}$$

From Eq. (2.43), 
$$F_{\text{dynam}} = \frac{Q_0}{1 - (\omega/\omega_n)} = \frac{6.7}{1 - (51.67/172.04)} = 9.58 \text{ kN}$$

Maximum force on the subgrade = 290 + 9.58 = 299.58 kN

Minimum force on the subgrade = 290 - 9.58 = 280.42 kN

## **2.11** $Q_0 = 200 \text{ kN}$

 $\omega$  = 6000 rad/min = 100 rad/s Weight of machine + foundation, W = 400 kN Spring constant, k = 120,000 kN/m

Natural angular frequency, 
$$\omega_n = \sqrt{\frac{k}{m}} = \sqrt{\frac{120,000 \times 10^3}{400 \times 10^3 / 9.81}} = 54.25 \text{ rad/s}$$

Dynamic force, 
$$F_{\text{dynam}} = \frac{Q_0}{1 - \omega/\omega_p} = \frac{200}{1 - (100/54.25)} = 237.16 \text{ kN}$$

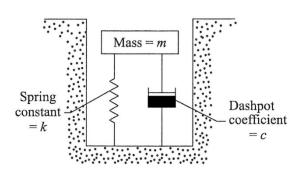
Maximum force on the subgrade = 400 + 237.16 = 637.16 kN

Minimum force on the subgrade = 400 - 237.16 = 162.84 kN

## 2.12 Weight of the body, W = 800 kN

Spring constant, k = 200,000 kN/m

Dashpot coefficient, c = 2340 kN-s/m



**a.** 
$$c_c = 2\sqrt{km} = 2\sqrt{200,000 \times 800/9.81} = 8077.1 \text{ kN-s/m}$$

**b.** Damping ratio, 
$$D = \frac{c}{c_c} = \frac{2340}{8077.1} = 0.29$$

c. 
$$\delta = \frac{2\pi D}{\sqrt{1 - D^2}} = \frac{2\pi \times 0.29}{\sqrt{1 - 0.29^2}} = 1.9$$

**d.** 
$$f_d = \sqrt{1 - D^2} f_n$$
;  $f_n = \frac{1}{2\pi} \sqrt{\frac{200,000 \times 9.81}{800}} = 7.88 \text{ Hz}$ 

$$f_d = \sqrt{1 - 0.29^2} \times 7.88 =$$
**7.54 Hz**

2.13 Weight of the body, W = 800 kNSpring constant, k = 200,000 kN/mDashpot coefficient, c = 2340 kN-s/m  $Q_0 = 25 \text{ kN}$ Operating frequency,  $\omega = 100 \text{ rad/s}$ 

**a.** Natural circular frequency, 
$$\omega_n = \sqrt{\frac{k}{m}} = \sqrt{\frac{200,000 \times 9.81}{800}} = 49.52 \text{ rad/s}$$

From Problem 2.12, damping ratio, D = 0.29

From Eq. (2.28), the amplitude of vertical vibration of the foundation is

$$Z = \frac{(Q_0/k)}{\sqrt{[1 - (\omega^2/\omega_n^2)]^2 + 4D^2(\omega^2/\omega_n^2)}}$$

$$= \frac{(25/200,000)}{\sqrt{[1 - (100^2/49.52^2)]^2 + 4 \times 0.29^2(100^2/49.52^2)}}$$

$$= 3.795 \times 10^{-5} \text{m} = 3.795 \times 10^{-2} \text{ mm}$$

**b.** From Eq. (2.90), the maximum dynamic force transmitted to the subgrade is

$$Z\sqrt{k^2 + (c\omega)^2} = (3.795 \times 10^{-5})\sqrt{200,000^2 + (2340 \times 100)^2} = 11.68 \text{ kN}$$